

\therefore ① reduces to

$$f_1(t', \vec{F}(t', \vec{x}')) = f_1(t', \vec{x}'')$$

for $d\vec{x}^k d\vec{x}^l$:-

$$\textcircled{3} \quad f_{3ij}(t', \vec{F}) \frac{\partial F^i}{\partial x^{lk}} \frac{\partial F^j}{\partial x^{ll}} = f_{3kl}(t', \vec{x}')$$

Homogeneity :-

Given any two points : (t, \vec{x}) & (t, \vec{y}) ,
there is an isometry \vec{F} such that

$$\vec{F}(t, \vec{x}') = \vec{y}$$

This implies $f_1(t', \vec{y}) = f_1(t', \vec{x})$ for any pair of points (\vec{x}, \vec{y}) ~~in space~~ in space
[follows from ①]

$$\Rightarrow [f_1(t', \vec{x}') = f_1(t')] \quad (\text{indep. of } \vec{x}')$$

(Isotropy is not going to give any further restriction on f_1 bcos anyway it is indep. of \vec{x}')

$$\# f_{3ij}(t', \vec{F}) \frac{\partial F^i}{\partial x^{lk}} \frac{\partial F^j}{\partial x^{ll}} = f_{3kl}(t', \vec{x}')$$

Fix t' (think of it as a parameter without thinking 4D spacetime) & think of f_{3ij} as a 3-dim. metric.

then, $\vec{x}^i = F^i(\vec{x}')$ is an isometry of the 3-dimensional metric $f_{3ij}(t', \vec{x}')$ for every t' .

Geometries associated to the space we consider here are homogeneous & isotropic.

$$ds_3^2 = f_{3ij} (t, \vec{x}) dx^i dx^j$$

& make a coord. fns. $x^i = F^i (\vec{x})$

then this is an isometry of the 3-d metric

$$\text{if } \boxed{f_{ij}(t, \vec{x}) \frac{\partial F^i}{\partial x^k} \frac{\partial F^j}{\partial x^l} = f_{kl}(t, \vec{x}^i)}$$

is satisfied.

List of homogeneous
and isotropic metrics

in $D = 3$

① flat space :

$$\begin{aligned} & f_{3ij} dx^i dx^j \\ &= \hat{f}(t) \left\{ (dx^1)^2 + (dx^2)^2 + (dx^3)^2 \right\} \\ &\quad \text{arbitrary fn of time} \end{aligned}$$

$\vec{x} \rightarrow \vec{x} + \vec{a}$: establishes homogeneity

$SO(3)$ rotation around origin \rightarrow isometry
establishes isotropy

②

Surface of a 3-dimensional sphere S^3

$$\sum_{i=1}^4 (z_i)^2 = R^2$$

$$ds_4^2 = dz^i dz^i$$

$SO(4)$

Since it is
scalar
-ve &
+ve
curvature
metric

Given any 2 pts.
on the 2D sphere S^2 ,
there is a rot. about
origin which takes
first pt. to the other

③ Constant -ve curvature metric :

$$z_4^2 - (z_1^2 + z_2^2 + z_3^2) = R^2$$

$$ds^2 = -(dz_4)^2 + \sum_{i=1}^3 (dz_i)^2$$

Ricci scalar
is const. but
tre → in our
notation

(A homogeneous metric should have a const. 3-d curvature.

But a const. 3-d Ricci scalar doesn't imply homogeneous metric bcos it only gives one prop. of the space)

~~$$g_3 = f(t) dt^2 + f_{3ij}(\vec{x}, t) dx^i dx^j$$~~

$$(i, j = 1, 2, \dots, 3)$$

Isometries:-

$$\begin{aligned} t &= t' \\ x^i &= f^i(\vec{x}') \end{aligned}$$

$$ds_3^2 = f_{3ij}(\vec{x}', t) dx^i dx^j$$

List of homogeneous & isotropic metrics
in D = 3

① flat space:-

$$\begin{aligned} f_{3ij} dx^i dx^j &= f(t) \{ (dx^1)^2 + (dx^2)^2 + (dx^3)^2 \} \\ &= f(t) \{ dx^2 + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \} \end{aligned}$$

② ~~3-dimensional sphere~~ S^3 :-

$$(z_1^2 + z_2^2 + z_3^2 + z_4^2) = R^2 \quad (1)$$

$$ds^2 = dz_1^2 + dz_2^2 + dz_3^2 + dz_4^2 \quad (2)$$

embedding space metric

4D flat metric

Analogous to sphere in 3d

$$\begin{aligned}
 z_4 &= R \cos \psi \\
 z_3 &= R \sin \psi \cos \theta \\
 z_1 &= R \sin \psi \sin \theta \cos \phi \\
 z_2 &= R \sin \psi \sin \theta \sin \phi
 \end{aligned}$$

θ, ϕ, ψ can be taken as the 3 indep. coordinates on S^3

~~Ex:~~ Check that

$$ds_3^2 = ds_4^2 \Big|_{\text{sphere}} = R^2 \left\{ d\psi^2 + \sin^2 \psi (d\theta^2 + \sin^2 \theta d\phi^2) \right\}$$

R is const. & so we don't vary R

$$\lambda = \sin \psi$$

$$dx = \cos \psi d\phi = \sqrt{1-\lambda^2} d\phi$$

$$ds_3^2 = R^2 \left\{ \frac{dx^2}{1-\lambda^2} + \lambda^2 d\theta^2 + \lambda^2 \sin^2 \theta d\phi^2 \right\}$$

Now, ds_4^2 is invariant under

$$\begin{pmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{pmatrix} \rightarrow \textcircled{U} \begin{pmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{pmatrix}$$

orthogonal matrix

$$\text{where } U^T U = \mathbb{I} \rightarrow 4 \times 4$$

(z_1, z_2, z_3, z_4) satisfies $z_1^2 + z_2^2 + z_3^2 + z_4^2 = R^2$,
then (z'_1, z'_2, z'_3, z'_4) also satisfies $\sum_{i=1}^4 z'_i{}^2 = R^2$

Any rot. is an isometry, analysing the eqns ① & ②

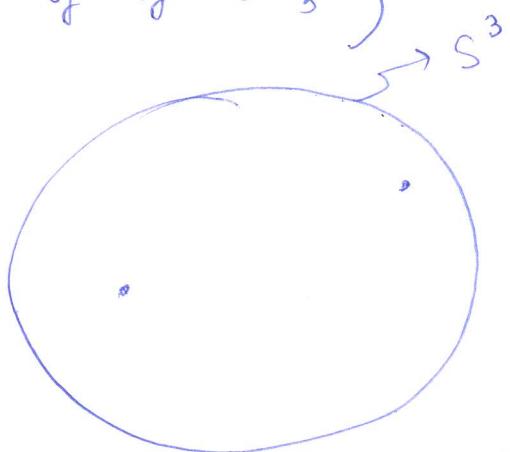
→ induces an isometry on the sphere

Take 2 pts. on the sphere \rightarrow Rotate it by ' U '.
 Distance is preserved bcos distance here is compared
 with metric of the embedding space $\Rightarrow S^3$ is isotropic

$$R \begin{pmatrix} \sin \varphi' \sin \theta' \cos \phi' \\ \sin \varphi' \sin \theta' \sin \phi' \\ \sin \varphi' \cos \theta' \\ \cos \varphi' \end{pmatrix} = R U \begin{pmatrix} \sin \varphi \cos \theta \cos \phi \\ \sin \varphi \cos \theta \sin \phi \\ \sin \varphi \cos \theta \\ \cos \varphi \end{pmatrix}$$

(Bcos of orthonormality, one eqn. is trivial)

(Applying the above eqns., we will see that rotm. is an isometry of ds_3^2)



① Given any 2 pts., we can find an isometry which takes us from one to another - this is by $SO(4)$
 \rightarrow Homogeneity is satisfied

$$(2) \quad \{x_0^M + \delta x^M\} \quad \{x_0^M + \delta y^M\}$$

$$g_{\mu\nu}(x_0) \delta x^M \delta x^\nu - g_{\mu\nu}(x_0) \delta y^M \delta y^\nu$$

x_0

Taking A to
 A' is an isometry
 \rightarrow homogeneity

That isometry must be such that even for $\{x_0^M + \lambda \delta x^M\}$, $\{x_0^M + \lambda \delta y^M\}$, the same isometry should take

from $\{x_0^M + \lambda \delta x^M\}$ to $\{x_0^M + \lambda \delta y^M\} \rightarrow$ for isotropy

It's some kind of rotation to

[the isometry should keep x_0^M fixed \rightarrow take $\lambda = 0$]

Choose a point :- $4' = \circ$

If it is isotropic around the North pole, it is isotropic about any other pt. Here it is so that preserves $4' = \circ$

$$\begin{pmatrix} z_1 \\ z_2 \\ z_3 \\ z_4 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$$

pt. on the sphere & on the z -axis

$$U = \begin{pmatrix} U_3 & 0 \\ 0 & 1 \end{pmatrix}$$

U_3 : 3×3 orthogonal matrix

This proves the space is also isotropic

③ Hyperboloid

$$z_4^2 - (z_1^2 + z_2^2 + z_3^2) = R^2$$

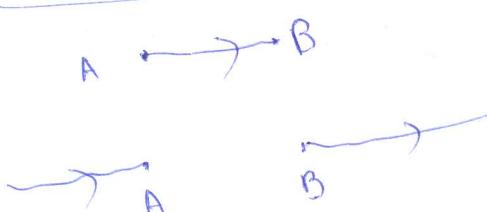
$$ds^2 = -(dz_4)^2 + \sum_{i=1}^3 (dz_i)^2$$

$$|z_4| > R \xrightarrow{\text{this means}}$$

$z_4 > R$ or $z_4 < -R$

(We choose one particular branch bcos our 3-d space is connected & we will never know about the disconnected part)

so we have 2 disconnected branches just like hyperbola



(these 2 paths aren't deformable to one another if A & B are identified — our universe may be like this (not simply connected))

Choose the branch :- $z_4 > R \rightarrow$ Three dim space

Coordinates :-

$$z_4 = R \cosh \psi$$

$$z_3 = R \sinh \psi \cos \theta$$

$$z_2 = R \sinh \psi \sin \theta \cos \phi$$

$$z_1 = R \sinh \psi \sin \theta \sin \phi$$

$$\cancel{ds^2} = ds^2_4 = R^2 \left\{ d\psi^2 + \sinh^2 \psi (d\theta^2 + \sin^2 \theta d\phi^2) \right\}$$

hyperboloid

The particular surface on which the induced metric is introduced has an induced Euclidean metric (it need not have been the case for other surfaces). At the end whatever metric we get should describe an Euclidean space. This is imp.

$$\text{Take: } x = \sinh \psi$$

$$\text{Then } ds^2_3 = R^2 \left\{ \frac{dx^2}{1+x^2} + x^2 d\theta^2 + x^2 \sin^2 \theta d\phi^2 \right\}$$

4-dim. Lorentz ts. maps a point on the hyperboloid to another point on the hyperboloid and preserves the form of the metric $\rightarrow SO(3,1)$ group of isometries

(the 3d metric is derived from the 4d metric. So if the ts. preserves the 4d metric & the eqn. $z_4^2 - \sum_{i=1}^3 z_i^2 = R^2$, it should preserve the 3d metric as well)

Homogeneous \rightarrow (bcos by Lcr. Trs. we can take one Lor. vector to another \rightarrow one pt. on the surface of hyperboloid to another)

Isotropy \rightarrow choose $\varphi = 0$, $z = R \begin{pmatrix} 0 \\ 0 \\ 0 \\ 1 \end{pmatrix}$

(Find a set of isometries which preserves this pt. & take us from one $\xrightarrow{\text{another}}$ of any 2 pts. equidistant from z)

Isometry follows from : - $U = \begin{pmatrix} U_3 & 0 \\ 0 & 1 \end{pmatrix}$

Homogeneous and isotropic cosmological metric : -

$$ds^2 = -f_1(t) dt^2 + \hat{f}(t) \left\{ \frac{dr^2}{1-kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right\}$$

$$k = \begin{cases} 0 & \rightarrow \text{flat space (zero curvature)} \\ 1 & \rightarrow \text{sphere (positive ")} \\ -1 & \rightarrow \text{Hyperboloid (negative ")} \end{cases}$$

Under $t \rightarrow F^0(t)$, (we don't violate any of the assumptions we made earlier - we don't violate the idea of cosmic time & hence the cosmological principle - of course $t \rightarrow F(t, \bar{x})$ isn't allowed)

$$-f_1(F^0(t')) \left(\frac{dF^0}{dt'} \right)^2 dt'^2 = dt'^2$$

if we choose F^0 such that

$$\frac{dF^0}{dt'} = \left(\sqrt{f_1(F_0(t))} \right)^{-1}$$

$$\therefore ds^2 = -dt^2 + \underbrace{f(F^0(t'))}_{(\lambda(t'))^2} \left\{ \frac{dr^2}{1-kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right\}$$

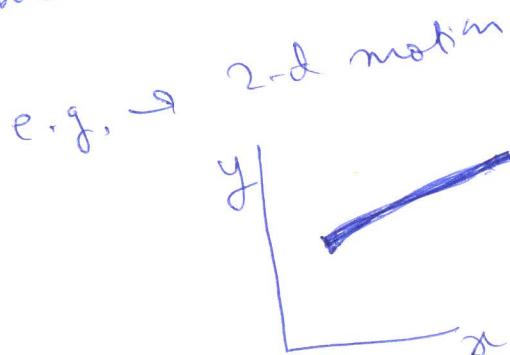
$$\Rightarrow ds^2 = -dt^2 + (\lambda(t))^2 \left\{ \frac{dr^2}{1-kr^2} + r^2 d\theta^2 + r^2 \sin^2 \theta d\phi^2 \right\}$$

Here, $\lambda(t)$ is known as the scale factor.
 (Homogeneity & isotropy don't restrict $\lambda(t)$)

If we know the avg. matter dist. in universe, we can find how λ evolves in time from Einstein's eqns.

If data about λ is available, matter content can be found from Einstein's eqns.

~~Ex:~~ Consider the eqn. for geodesic ϕ in the 4-d space.
 Show that if we project it onto the 3-dim. space (forget $x^0=t$), then it is a geodesic in the 3-dimensional space.



projection of the full trajectory in the space part

To get the time evolution, we need to draw it in 3-d with time along z-axis

$ds^2 = -dt^2 + (\lambda(t))^2 g_{ij}(\bar{x}) dx^i dx^j$ from the COORDINATES

For any metric of this form the statement holds — only in this case we can talk about the 3-d geodesic without reference to t .

We have to show the dx^i -eqns are the ones in which terms like Γ_{00}^i or Γ_{0j}^i are absent in

$$\frac{d^2 x^\mu}{ds^2} + \Gamma_{\nu\mu}^\mu \frac{dx^\nu}{ds} \frac{dx^\rho}{ds} = 0$$

Take 2 points P & Q in this 3-d space:



Consider a light ray that starts at P at $t=t_1$ & ends at Q at $t=t_2$.

Given P, Q, and t_1 , we want to calculate t_2 .

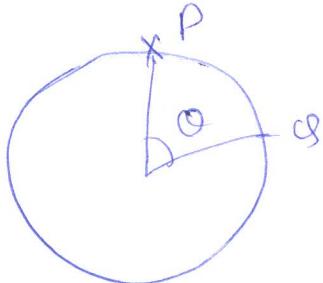
Firstly, $ds^2 = 0$ bcs light travels along null geodesic

$$\therefore dt^2 = (\lambda(t))^2 g_{ij}(\bar{x}) dx^i dx^j$$

$$\begin{aligned} \Rightarrow \int_{t_1}^{t_2} \frac{dt}{\lambda(t)} &= \int_P^Q \sqrt{g_{ij}(\bar{x}) dx^i dx^j} \\ &= \int_P^Q \sqrt{g_{ij}(\bar{x}) \frac{dx^i}{du} \frac{dx^j}{du}} du \end{aligned}$$

where α is the parameter labelling the path.

the path connecting P & Q must be a geodesic connecting P, Q



\therefore sphere is homogeneous, we choose our coord. such that P is at the North pole — then the O -coord. of Q is the answer for the geodesic length from P to Q)

as is ~~for~~ proved in the exercise
→ null geodesic in 4-d Mink.
space gives us null geodesic in 3-d space

P emits another signal at $t_1 + \Delta t_2$
 Q receives it at $t_2 + \Delta t_2$.

$$\int_{t_1 + \Delta t_2}^{t_2 + \Delta t_2} \frac{dt}{\gamma(t)} = \int_P^Q \sqrt{g_{ij}(\bar{x}) \frac{dx^i}{du} \frac{dx^j}{du}} du$$

d₁, P

$$\Delta t_1 = \frac{1}{\nu}$$

intrinsic frequency of the source

Proper time of the light source sitting at P is the cosmic time

Observed frequency :-

$$\frac{1}{\Delta t_2} = \frac{1}{\Delta t_1} \frac{\lambda(t_1)}{\lambda(t_2)} = \nu \frac{\lambda(t_1)}{\lambda(t_2)}$$

Same source placed at Q will have frequency $\Delta t = \frac{1}{\nu}$

$$\therefore \boxed{\nu_{\text{obs}} = \nu_{\text{intrinsic}} \frac{\lambda(t_1)}{\lambda(t_2)}} \quad \textcircled{A}$$

t₁ :— current time to (of the observer)

we can't change t₁
not in our hand

we can change t₂ by looking at diff. stars at diff. distances.

One observes a series of lines & calculating the ratio of the lines, which is an invariant for a particular intrinsic spectrum, we can do the comparison.

(A) is a linear relation — ratio is same ---

~~24/8/07~~

$$v' = \frac{\lambda(t_1)}{\lambda(t_2)} v$$

source time

↓ observed frequency ↓ actual frequency

↓ observer time t_0

$v' = \frac{\lambda(t_1)}{\lambda(t_0)} v$

to → denotes the present time

(One observes ~~over~~ several spectral lines & calculating their ratios, which are the same always, finds the red-shift)

Expt. :-

$v' < v$ for faraway objects

$$\lambda(t_1) < \lambda(t_0)$$

$$t_1 < t_0$$

⇒ $\lambda(t)$ is increasing with Time.

⇒ Universe is expanding.

$$ds^2 = -dt^2 + (\lambda(t))^2 g_{ij}(\tilde{x}) dx^i dx^j$$

physical distance ⇒ distance measured in the metric $g_{ij}(\tilde{x}) \times \lambda(t)$

(∴ as $\lambda \uparrow$, phys. dist. ↑ for any any 2 points in the comoving coord.)

$$\text{Hubble constant } H_0 = \frac{1}{\lambda(t_0)} \frac{d\lambda(t)}{dt}$$

measures rate of change of λ at present time
— we normalise it by $\lambda(t_0)$

Det. $\frac{\lambda(t_1)}{\lambda(t_0)}$ by averaging over many stars which are nearly at the same distance from us — this is bcos observing a single star, the peculiar vel. will come in our obsrvn.

$$\frac{\lambda(t)}{\lambda(t_0)} = 1 + f_{10}(t_0) (t - t_0) - \frac{1}{2} q_0(t_0) \left(H_0(t_0) \right)^2 (t - t_0)^2 + \dots$$

$$q_0(t_0) = - \frac{1}{H_0(t_0)^2 \lambda(t_0)} \frac{d^2 \lambda(t)}{dt^2}$$

\hookrightarrow deceleration parameter

It was believed that universe is decelerating & so historically, q_0 was introduced

Red shift parameter

$$z(t_1) = \frac{\lambda(t_0)}{\lambda(t_1)} - 1$$

\rightarrow this is due to expansion of universe.

For faraway objects, grav. red-shifts are small compared to cosmological red-shift)

z is the measurement of time - ~~time~~

z is directly measurable - z can be converted to scale factor, which can be converted to time

(For consistency of our eqns, our energy-mom. tensor should have same isometries as ~~g_{μν}~~)

$T_{\mu\nu}$, being a source for $g_{\mu\nu}$, must have the same isometries as $g_{\mu\nu}$.

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -8\pi G T_{\mu\nu}$$

($R_{\mu\nu}$, R are form-invariant bcs $g_{\mu\nu}$ is form-invariant - $R_{\mu\nu}$ & R are constructed from $g_{\mu\nu}$ $\Rightarrow T_{\mu\nu}$ must also have similar prop.)

General coord. trs :-

$$T'_{\mu\nu}(x') \frac{\partial x'^{\mu}}{\partial x^{\rho}} \frac{\partial x'^{\nu}}{\partial x^{\sigma}} = T_{\rho\sigma}(x)$$

Isometry $\Rightarrow T_{\mu\nu}(x') = T_{\mu\nu}(x')$

$$\Rightarrow T_{\mu\nu}(x') \frac{\partial x'^{\mu}}{\partial x^{\rho}} \frac{\partial x'^{\nu}}{\partial x^{\sigma}} = T_{\rho\sigma}(x)$$

$$ds^2 = -dt^2 + (x^i)^2 g_{ij}(\vec{x}) dx^i dx^j$$

If the tensor in consideration is related to $g_{\mu\nu}$, it should have the same isometries — e.g. for EM field, the energy-mom. tensor $T_{\mu\nu}$ should have the same isometry — of course ~~An can have diff.~~, it may not obey the isometry, while $T_{\mu\nu}$ obeys it, it is very diff. to have such a situation → so better ~~An~~ An also obeys it or say the pot. An obeys it

$$t' = t$$

$$x'^i = f^i(\vec{x})$$

$$T_{00}(x') = T_{00}(x)$$

$$T_{00}(t, \vec{x}') = T_{00}(t, \vec{x}) \quad \text{--- (1)}$$

~~$T_{0i}(t, \vec{x}')$~~ $T_{0i}(t, \vec{x}) = T_{0j}(t, \vec{x}') \frac{\partial x'^j}{\partial x^i} \quad \text{--- (2)}$

$$T_{ij}(t, \vec{x}) = T_{kl}(t, \vec{x}') \frac{\partial x'^k}{\partial x^i} \frac{\partial x'^l}{\partial x^j} \quad \text{--- (3)}$$

$$\textcircled{1} \text{ implies } T_{00}(t, \vec{x}') = p(t)$$

\textcircled{2} & \textcircled{3} imply \rightarrow regarding t as a fixed parameter
 $T_{0i}(t, \vec{x})$ is a form-invariant covariant rank 1 tensor in 3-dimension.
 $T_{ij}(t, \vec{x})$ is a form invariant covariant rank 2 tensor in 3-dimensions.
 (form-inv. tensors are very hard to find)

$\kappa=0$ case :- (flat space)

$$V(\vec{x}) = \vec{V}(\vec{x} + \vec{a})$$

$\Rightarrow \vec{V}$ is constant

$\Rightarrow \vec{V} = 0$ (isotropy)

$$V_{ij}(\vec{x}) = V_{ij} = \text{constant}$$

$$x^{1^i} = R_{ij} x^{j^i}$$

$$\begin{matrix} V_{ij} \\ // \\ V_{ij} \end{matrix} = R_{ik} R_{jl} V_{kl} \Rightarrow [V = C \delta_{ij}]$$

$$V = C \tilde{g}_{ij}$$

(bcz in flat space $\tilde{g}_{ij} = \delta_{ij}$)

(Analysis for $\kappa = \pm 1$ cases also give the same result, though the calculations are more involved)

Soln :- $T_{00}(t, \vec{x}) = P(t)$

$$T_{0i}(t, \vec{x}) = 0$$

$$T_{ij}(t, \vec{x}) = f(t) \tilde{g}_{ij} = f(t) \lambda(t)^{-2} g_{ij}$$

$f(t)$

most general form when find rest as two rest has the same isotropies as you

called pressure bcz it mimics pressure

$$D_\mu T^{\mu\nu} = 0$$

Ex:- show that this gives :-

$$\frac{d}{dt}(f \lambda^3) = -3f \lambda^2 \dot{\lambda}$$

Note :- No one gives us $f(t)$ - has to be determined from dynamics - of we ϕ may be able to find $f(t_0)$ by observ.

~~Ex:~~ $ds^2 = -dt^2 + \lambda(t)^2 \left\{ \frac{dx^2}{1-kx^2} + x^2 d\theta^2 + x^2 \sin^2 \theta d\phi^2 \right\}$

Check that :-

$$R_{00} = \frac{3\ddot{x}}{\lambda}, R_{ij} = -(\lambda\ddot{x} + 2\dot{x}^2 + 2k) \tilde{g}_{ij}$$

$$R = g^{00} R_{00} + g^{ij} R_{ij} = -\frac{6\ddot{x}}{\lambda} - 6\left(\frac{\dot{x}}{\lambda}\right)^2 - 6k/\lambda^2$$

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -8\pi G T_{\mu\nu}$$

~~Ex:~~ 00-component gives

$$-8\pi G f = -3\left(\frac{\dot{x}}{\lambda}\right)^2 - 3k/\lambda^2 \quad \text{--- (1)}$$

& ij-component gives

$$-8\pi G f = 2\frac{\ddot{x}}{\lambda} + \left(\frac{\dot{x}}{\lambda}\right)^2 + \frac{k}{\lambda^2} \quad \text{--- (2)}$$

(Only one eqn. bcos both LHS & RHS are prop. to g_{ij})

(1) & (2) aren't independent bcos \rightarrow

$D_\mu (R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu}) = 0$ is an identity

~~Ex:~~ Take $\frac{d}{dt} (1)$ and substitute \ddot{x} from (2)
gives

$$\frac{d}{dt} (8x^3) = -3\beta x^2 \dot{x}$$

aren't indep. bcos (2) can be seen to follow from (1)
& $\frac{d}{dt} (8x^3) = -3\beta x^2 \dot{x}$. Remember we have the Bianchi identity

So, we can work with the eqns/

$$\frac{d}{dt}(f\lambda^3) = -3\beta\lambda^2\dot{\lambda}$$

$$3\left(\frac{\dot{\lambda}}{\lambda}\right)^2 + 3k/\lambda^2 = 8\pi G f$$

Energy-mom
should follow
as a
consequence
of Einstein
eqn by
using
Bianchi
identities
→ it's no
surprise
② isn't
indep.

($\lambda(t)$, $f(t)$, $\beta(t)$) → 3 unknown fns

so 2 first order diff. eqns for 3
unknowns — so time evolution
isn't det. completely)

Unknown functions $\Rightarrow f(t), \beta(t), \lambda(t)$

→ Need some more information.

(This is given by the prop. of energy-mom. tensor — not
that we need to know it as a fn of t)

Additional information needed : Equation
of state

functional relationship

gives us
between β & f

(This eqn. of state
is indep. of background)

$$T_{00} = -\rho(t) g_{00}$$

$$T_{ij} = p(t) g_{ij}$$

(T_{00} transforms exactly as g_{00}

$$T_{ij} \quad " \quad " \quad " \quad g_{ij}$$

→ so relation betw. ρ & p doesn't depend on
the cond. frame we have chosen)

We can show that
relation betw. ρ & p
won't change under
 $t \rightarrow f(t)$

$$g_{ij} \rightarrow \tilde{g}_{ij}(\tilde{x}')$$

Possible sources in cosmology

① Non relativistic matter. \rightarrow their rel. $\ll c$

② Radiation

③ Cosmological constant

(can be either thought of as a source in $T_{\mu\nu}$, or as a term modifying Einstein's eqn)

$$R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -8\pi G T_{\mu\nu} + \Lambda g_{\mu\nu}$$

\hookrightarrow Cosmological constant

$$\textcircled{1} \Rightarrow \phi = 0 \quad (\text{Dark matter is included here})$$

$$\textcircled{2} \Rightarrow \phi = \frac{8}{3}$$

$$\textcircled{3} \Rightarrow R_{\mu\nu} - \frac{1}{2} R g_{\mu\nu} = -8\pi G \left(T_{\mu\nu} - \frac{\Lambda}{8\pi G} g_{\mu\nu} \right)$$

$$\therefore T_{\mu\nu}^{\text{cos}} = -\frac{\Lambda}{8\pi G} g_{\mu\nu} \Rightarrow \phi = \frac{\Lambda}{8\pi G}$$

$$\phi = -\frac{\Lambda}{8\pi G}$$

Recall:
 $T_{\mu\nu} = -g(\mu) g_{\nu\lambda} T^{\lambda}_{\nu}$
 $T_{ij} = \phi(\lambda) g_{ij}$

(This is sometimes called dark energy)

(when we talk about NR matter, we essentially mean temp. $T = 0$)

Imagine int. beh. matter & radiation is so small that they aren't equilibrating --)

$$\text{Now, } \overset{\circ}{T}{}^{\mu\nu} = \sum_n m_n \int du \left(\sqrt{-\det g} \right)^{-1} \frac{\partial x^\mu}{\partial u} \frac{\partial x^\nu}{\partial u} \delta^{(n)}_{(\mu} \delta^{(\nu)}_{X(u))}$$

Non-relativistic matter :- $\boxed{(x^0 = ct)}$

$$\left| \frac{\partial x^i}{\partial \tau} \right| \ll \frac{\partial x^0}{\partial \tau}$$

$$|T^{0i}| \ll \rho \cdot c$$

So, $T_{ij} = 0$ for non-relativistic matter
 $\Rightarrow p = 0$