### Weak Measurements, Quantum State Collapse and the Born Rule

#### **Apoorva Patel**

Centre for High Energy Physics Indian Institute of Science, Bangalore

8 December 2015, QIPA-2015, HRI, Allahabad

N. Gisin, Phys. Rev. Lett. 52 (1984) 1657 Apoorva Patel and Parveen Kumar, arXiv:1509.08253



# **Axioms of Quantum Dynamics**

(1) Unitary evolution (Schrödinger):  $i\frac{d}{dt}|\psi\rangle = H|\psi\rangle$ ,  $i\frac{d}{dt}\rho = [H,\rho]$ . Continuous, Reversible, Deterministic. Pure state evolves to pure state.



# **Axioms of Quantum Dynamics**

(1) Unitary evolution (Schrödinger):

 $i\frac{d}{dt}|\psi\rangle = H|\psi\rangle$ ,  $i\frac{d}{dt}\rho = [H,\rho]$ . Continuous, Reversible, Deterministic. Pure state evolves to pure state.

(2) Projective measurement (von Neumann):

 $|\psi\rangle \longrightarrow P_i |\psi\rangle/|P_i |\psi\rangle|, \ P_i = P_i^{\dagger}, \ P_i P_j = P_i \delta_{ij}, \ \sum_i P_i = I.$ 

Discontinuous, Irreversible, Probabilistic choice of "*i*". Pure state evolves to pure state. Consistent on repetition.

 $\{P_i\}$  is fixed by the measurement apparatus eigenstates. But there is no prediction for which "*i*" will occur in a particular experimental run. "The measurement problem"



### **Axioms of Quantum Dynamics**

(1) Unitary evolution (Schrödinger):

 $i\frac{d}{dt}|\psi\rangle = H|\psi\rangle$ ,  $i\frac{d}{dt}\rho = [H,\rho]$ . Continuous, Reversible, Deterministic. Pure state evolves to pure state.

(2) Projective measurement (von Neumann):

 $|\psi\rangle \longrightarrow P_i |\psi\rangle/|P_i |\psi\rangle|, P_i = P_i^{\dagger}, P_i P_j = P_i \delta_{ij}, \sum_i P_i = I.$ Discontinuous, Irreversible, Probabilistic choice of "*i*".

Pure state evolves to pure state. Consistent on repetition.

 $\{P_i\}$  is fixed by the measurement apparatus eigenstates. But there is no prediction for which "*i*" will occur in a particular experimental run. "The measurement problem"

Instead, with Born rule and ensemble interpretation,  $prob(i) = \langle \psi | P_i | \psi \rangle = Tr(P_i \rho) , \quad \rho \longrightarrow \sum_i P_i \rho P_i .$ Pure state evolves to mixed state. Predicted expectation values are averages over many experimental runs.

# **Quantum Measurement Terminology**



The evolution steps involved in the quantum measurement process for a qubit  $(\rho_i \text{ and } \rho_f \text{ are pure states, while } \rho_r \text{ is obtained from an entangled state}):$ (a) Decoherence deterministically entangles the system with its environment, and drives the off-diagonal reduced density matrix components to zero. (b) Quantum jump removes the system-apparatus entanglement, and probabilistically converts the diagonal reduced density matrix into a measurement eigenstate. (c) Collapse is the overall process that yields measurement eigenstates probabilistically, and it may or may not go through decoherence.



# **Terminology (contd.)**

Decoherence entangles the observed system degrees of freedom with the unobserved environmental degrees of freedom. Sum over the unobserved degrees of freedom yields a reduced mixed state, with the same structure as the ensemble of statistical mechanics. It quantitatively explains how the off-diagonal elements of  $\rho$  decay.



# **Terminology (contd.)**

Decoherence entangles the observed system degrees of freedom with the unobserved environmental degrees of freedom. Sum over the unobserved degrees of freedom yields a reduced mixed state, with the same structure as the ensemble of statistical mechanics. It quantitatively explains how the off-diagonal elements of  $\rho$  decay.

von Neumann interaction is a particular instance of the decoherence paradigm. It creates perfect entanglement between the measured eigenstates of the system and the pointer basis states of the apparatus.

 $H_{\rm vN} = g \ x_S \otimes p_A \ : \quad |x\rangle_S |0\rangle_A \longrightarrow |x\rangle_S |x\rangle_A$ 

For a qubit, this is the C-not operation.



# **Terminology (contd.)**

Decoherence entangles the observed system degrees of freedom with the unobserved environmental degrees of freedom. Sum over the unobserved degrees of freedom yields a reduced mixed state, with the same structure as the ensemble of statistical mechanics. It quantitatively explains how the off-diagonal elements of  $\rho$  decay.

von Neumann interaction is a particular instance of the decoherence paradigm. It creates perfect entanglement between the measured eigenstates of the system and the pointer basis states of the apparatus.

 $H_{\rm vN} = g \ x_S \otimes p_A \ : \quad |x\rangle_S |0\rangle_A \longrightarrow |x\rangle_S |x\rangle_A$ 

For a qubit, this is the C-not operation.

Quantum jump is probabilistic. It defines which interactions of a system with its surroundings are measurements. A measurement interaction is the one where the apparatus cannot remain in a superposition of pointer states.

### **Weak Measurements**

Information about the measured observable is extracted from the system at a slow rate (e.g. by weak coupling). Stretching out of the time scale can allow one to monitor how the system collapses to a measurement eigenstate.



### Weak Measurements

Information about the measured observable is extracted from the system at a slow rate (e.g. by weak coupling). Stretching out of the time scale can allow one to monitor how the system collapses to a measurement eigenstate.

#### New questions:

- How is the projection replaced by a continuous evolution?
- What is the local evolution rule during measurement?
- What is the state if the measurement is left incomplete?
- How is the ensemble to be interpreted?
- How should multipartite measurements be described?



### Weak Measurements

Information about the measured observable is extracted from the system at a slow rate (e.g. by weak coupling). Stretching out of the time scale can allow one to monitor how the system collapses to a measurement eigenstate.

#### New questions:

- How is the projection replaced by a continuous evolution?
- What is the local evolution rule during measurement?
- What is the state if the measurement is left incomplete?
- How is the ensemble to be interpreted?
- How should multipartite measurements be described?

The answers are important for increasing accuracy of quantum control and feedback. Knowledge of what happens in a particular experimental run (and not the ensemble average) can improve efficiency and stability.

The projective measurement axiom needs to be replaced by a different continuous stochastic dynamics.

Quantum jump can be realised as addition of noise to a deterministic process. Such a conversion into a Langevin equation retains ensemble interpretation. But properties of quantum measurements impose strong constraints.



Quantum jump can be realised as addition of noise to a deterministic process. Such a conversion into a Langevin equation retains ensemble interpretation. But properties of quantum measurements impose strong constraints.

To ensure repeatability of measurement outcomes, the measurement eigenstates need to be fixed points of the evolution. The noise has to vanish at the fixed points.
⇒ The deterministic part of evolution must be nonlinear.



Quantum jump can be realised as addition of noise to a deterministic process. Such a conversion into a Langevin equation retains ensemble interpretation. But properties of quantum measurements impose strong constraints.

To ensure repeatability of measurement outcomes, the measurement eigenstates need to be fixed points of the evolution. The noise has to vanish at the fixed points.
⇒ The deterministic part of evolution must be nonlinear.

 Probabilities of measurement outcomes need to be maintained during evolution. Lack of simultaneity in special relativity must not conflict with multipartite measurements.
⇒ The Born rule has to be a constant of evolution during measurement, when averaged over the stochastic noise.



Quantum jump can be realised as addition of noise to a deterministic process. Such a conversion into a Langevin equation retains ensemble interpretation. But properties of quantum measurements impose strong constraints.

To ensure repeatability of measurement outcomes, the measurement eigenstates need to be fixed points of the evolution. The noise has to vanish at the fixed points.
⇒ The deterministic part of evolution must be nonlinear.

 Probabilities of measurement outcomes need to be maintained during evolution. Lack of simultaneity in special relativity must not conflict with multipartite measurements.
⇒ The Born rule has to be a constant of evolution during measurement, when averaged over the stochastic noise.

Such a dynamical process exists!

Gisin (1984)



### **Salient Features**

A precise ratio of evolution towards the measurement eigenstates and unbiased white noise is needed to reproduce the Born rule as a constant of evolution.

This is reminiscent of the "fluctuation-dissipation theorem" that connects diffusion and viscous damping, implying a common origin for both in molecular scattering.



### **Salient Features**

A precise ratio of evolution towards the measurement eigenstates and unbiased white noise is needed to reproduce the Born rule as a constant of evolution.

This is reminiscent of the "fluctuation-dissipation theorem" that connects diffusion and viscous damping, implying a common origin for both in molecular scattering.

#### The measurement dynamics is completely local between the system and the apparatus, independent of any other environmental degrees of freedom.

This is also an indication that the deterministic and the stochastic contributions to the evolution arise from the same underlying dynamics.



### **Salient Features**

A precise ratio of evolution towards the measurement eigenstates and unbiased white noise is needed to reproduce the Born rule as a constant of evolution.

This is reminiscent of the "fluctuation-dissipation theorem" that connects diffusion and viscous damping, implying a common origin for both in molecular scattering.

#### The measurement dynamics is completely local between the system and the apparatus, independent of any other environmental degrees of freedom.

This is also an indication that the deterministic and the stochastic contributions to the evolution arise from the same underlying dynamics.

Technological advances allow us to monitor the quantum evolution during weak measurements. That would help us test the validity of the stochastic measurement process, and then figure out what may lie beyond.



# **Beyond Quantum Mechanics**

Physical:

(1) Hidden variables with novel dynamics may produce quantum mechanics as an effective theory, with extra rules supplementing Schrödinger's equation.

(2) Gravity can produce effects that modify quantum dynamics at macroscopic scales.



# **Beyond Quantum Mechanics**

Physical:

(1) Hidden variables with novel dynamics may produce quantum mechanics as an effective theory, with extra rules supplementing Schrödinger's equation.

(2) Gravity can produce effects that modify quantum dynamics at macroscopic scales.

Philosophical:

(1) What is real (ontology) may not be the same as what is observable (epistemology).

(2) Human beings have only limited capacity and cannot comprehend everything in the universe.



# **Beyond Quantum Mechanics**

Physical:

(1) Hidden variables with novel dynamics may produce quantum mechanics as an effective theory, with extra rules supplementing Schrödinger's equation.

(2) Gravity can produce effects that modify quantum dynamics at macroscopic scales.

Philosophical:

(1) What is real (ontology) may not be the same as what is observable (epistemology).

(2) Human beings have only limited capacity and cannot comprehend everything in the universe.

#### Bypass:

Many worlds interpretation—each evolutionary branch is a different world, and we only observe the measurement outcome corresponding to the world we live in.



Uncountable proliferation of evolutionary branches is highly ungainly.













Department of Tourism



Let the projective measurement arise from a continuous geodesic evolution, with parameter  $s \in [0, 1]$ :

 $|\psi\rangle \longrightarrow Q_i(s)|\psi\rangle/|Q_i(s)|\psi\rangle|$ ,  $Q_i(s) = (1-s)I + sP_i$ .

Then an individual quantum trajectory evolves as

$$\rho \longrightarrow \frac{(1-s)^2 \rho + s(1-s)(\rho P_i + P_i \rho) + s^2 P_i \rho P_i}{(1-s)^2 + (2s-s^2)Tr(P_i \rho)} , \quad Tr(\rho) = 1 .$$



Let the projective measurement arise from a continuous geodesic evolution, with parameter  $s \in [0, 1]$ :

 $|\psi\rangle \longrightarrow Q_i(s)|\psi\rangle/|Q_i(s)|\psi\rangle|$ ,  $Q_i(s) = (1-s)I + sP_i$ .

Then an individual quantum trajectory evolves as

$$\rho \longrightarrow \frac{(1-s)^2 \rho + s(1-s)(\rho P_i + P_i \rho) + s^2 P_i \rho P_i}{(1-s)^2 + (2s-s^2)Tr(P_i \rho)} , \quad Tr(\rho) = 1 .$$

Expansion around s = 0 gives the collapse equation:

$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho \ Tr(P_i\rho)] \ .$$

 $s \rightarrow gt$  in terms of the system-apparatus coupling g, and the "measurement time" t.



Let the projective measurement arise from a continuous geodesic evolution, with parameter  $s \in [0, 1]$ :

 $|\psi\rangle \longrightarrow Q_i(s)|\psi\rangle/|Q_i(s)|\psi\rangle|$ ,  $Q_i(s) = (1-s)I + sP_i$ .

Then an individual quantum trajectory evolves as

$$\rho \longrightarrow \frac{(1-s)^2 \rho + s(1-s)(\rho P_i + P_i \rho) + s^2 P_i \rho P_i}{(1-s)^2 + (2s-s^2)Tr(P_i \rho)} , \quad Tr(\rho) = 1 .$$

Expansion around s = 0 gives the collapse equation:

$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho Tr(P_i\rho)].$$

 $s \rightarrow gt$  in terms of the system-apparatus coupling g, and the "measurement time" t.

• This nonlinear evolution preserves pure states,

$$\rho^2 = \rho \Longrightarrow \frac{d}{dt}(\rho^2 - \rho) = \rho \frac{d}{dt}\rho + (\frac{d}{dt}\rho)\rho - \frac{d}{dt}\rho = 0 ,$$

in addition to maintaining  $Tr(\rho) = 1$ .



Let the projective measurement arise from a continuous geodesic evolution, with parameter  $s \in [0, 1]$ :

 $|\psi\rangle \longrightarrow Q_i(s)|\psi\rangle/|Q_i(s)|\psi\rangle|$ ,  $Q_i(s) = (1-s)I + sP_i$ .

Then an individual quantum trajectory evolves as

$$\rho \longrightarrow \frac{(1-s)^2 \rho + s(1-s)(\rho P_i + P_i \rho) + s^2 P_i \rho P_i}{(1-s)^2 + (2s-s^2)Tr(P_i \rho)} , \quad Tr(\rho) = 1 .$$

Expansion around s = 0 gives the collapse equation:

$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho \ Tr(P_i\rho)] \ .$$

 $s \rightarrow gt$  in terms of the system-apparatus coupling g, and the "measurement time" t.

#### • This nonlinear evolution preserves pure states,

$$\rho^2 = \rho \Longrightarrow \frac{d}{dt}(\rho^2 - \rho) = \rho \frac{d}{dt}\rho + (\frac{d}{dt}\rho)\rho - \frac{d}{dt}\rho = 0 ,$$
 in addition to maintaining  $Tr(\rho) = 1$ .

• Projective measurement is the fixed point of this equation:  $\frac{d}{dt}\rho = 0$  at  $\rho^* = P_i\rho P_i/Tr(P_i\rho)$ .



Convergence to fixed point makes the measurement consistent on repetition Measurements and Born Rule - p. 1

$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho Tr(P_i\rho)]$$



$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho Tr(P_i\rho)]$$

• In a bipartite setting,  $\{P_i\} = \{P_{i_1} \otimes P_{i_2}\}$ . The evolution is linear in the projection operators, and  $\sum_i P_i = I$ . So partial trace over the unobserved environment gives the same equation for the reduced density matrix for the system.

Purification is a consequence of the unchanged fixed point.



$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho Tr(P_i\rho)]$$

• In a bipartite setting,  $\{P_i\} = \{P_{i_1} \otimes P_{i_2}\}$ . The evolution is linear in the projection operators, and  $\sum_i P_i = I$ . So partial trace over the unobserved environment gives the same equation for the reduced density matrix for the system.

Purification is a consequence of the unchanged fixed point.

• Asymptotic convergence to the fixed point is exponential, with  $||\rho - P_i|| \sim e^{-2gt}$ , similar to the charging of a capacitor.



$$\frac{d}{dt}\rho = g[\rho P_i + P_i\rho - 2\rho Tr(P_i\rho)]$$

• In a bipartite setting,  $\{P_i\} = \{P_{i_1} \otimes P_{i_2}\}$ . The evolution is linear in the projection operators, and  $\sum_i P_i = I$ . So partial trace over the unobserved environment gives the same equation for the reduced density matrix for the system.

Purification is a consequence of the unchanged fixed point.

• Asymptotic convergence to the fixed point is exponential, with  $||\rho - P_i|| \sim e^{-2gt}$ , similar to the charging of a capacitor.

• For pure states, the collapse equation is:

 $\frac{d}{dt}\rho = -2g\mathcal{L}[\rho]P_i$ 

This structure (involving Lindblad operator) hints at an action-reaction relation between processes of decoherence and collapse, possibly following from a conservation law.

Interpretation: When  $\mathcal{L}[\rho]P_i$  decoheres the apparatus pointer state  $P_i$  (it cannot remain in superposition by definition), there is an equal and opposite effect  $-\mathcal{L}[\rho]P_i$  on the system state  $\rho$  leading to its collapse.



# **Ensemble of Quantum Trajectories**

The prefered basis  $\{P_i\}$  is fixed by the system-apparatus interaction, but a separate criterion is needed to determine which  $P_i$  will occur in a particular experimental run.

Quantum jump: The evolution trajectory is chosen at the start of the measurement and remains unaltered thereafter.

The Born rule fixes the probabilities of various quantum jumps.



# **Ensemble of Quantum Trajectories**

The prefered basis  $\{P_i\}$  is fixed by the system-apparatus interaction, but a separate criterion is needed to determine which  $P_i$  will occur in a particular experimental run.

Quantum jump: The evolution trajectory is chosen at the start of the measurement and remains unaltered thereafter.

The Born rule fixes the probabilities of various quantum jumps.

Such a choice may be justified for a "sudden impulsive measurement", but not for a "gradual weak measurement".

For describing evolution during weak measurements, we need a local dynamical rule governing quantum trajectories.



# **Ensemble of Quantum Trajectories**

The prefered basis  $\{P_i\}$  is fixed by the system-apparatus interaction, but a separate criterion is needed to determine which  $P_i$  will occur in a particular experimental run.

Quantum jump: The evolution trajectory is chosen at the start of the measurement and remains unaltered thereafter.

The Born rule fixes the probabilities of various quantum jumps.

Such a choice may be justified for a "sudden impulsive measurement", but not for a "gradual weak measurement".

For describing evolution during weak measurements, we need a local dynamical rule governing quantum trajectories.

Assign time-dependent real weights  $w_i(t)$  to the evolution trajectories for  $P_i$ , with  $\sum_i w_i = 1$ :

$$\frac{d}{dt}\rho = \sum_{i} w_i g[\rho P_i + P_i \rho - 2\rho Tr(P_i \rho)] \,.$$



### **Ensemble Evolution**

#### The trajectory averaged evolution is:

 $\frac{d}{dt}(P_j\rho P_k) = P_j\rho P_k g[w_j + w_k - 2\sum_i w_i Tr(P_i\rho)].$ 



### **Ensemble Evolution**

# The trajectory averaged evolution is: $\frac{d}{dt}(P_{j}\rho P_{k}) = P_{j}\rho P_{k} g[w_{j} + w_{k} - 2\sum_{i} w_{i}Tr(P_{i}\rho)].$ Diagonal projections of $\rho$ fully determine the evolution: $\frac{2}{P_{j}\rho P_{k}}\frac{d}{dt}(P_{j}\rho P_{k}) = \frac{1}{P_{j}\rho P_{j}}\frac{d}{dt}(P_{j}\rho P_{j}) + \frac{1}{P_{k}\rho P_{k}}\frac{d}{dt}(P_{k}\rho P_{k})$ For one-dimensional projections, $P_{j}\rho(t)P_{j} = d_{j}(t)P_{j}$ , $d_{j} \geq 0, \quad P_{j}\rho(t)P_{k} = P_{j}\rho(0)P_{k}\left[\frac{d_{j}(t)d_{k}(t)}{d_{j}(0)d_{k}(0)}\right]^{1/2}.$ Phases of the off-diagonal projections $P_{j}\rho P_{k}$ do not change.

Also, off-diagonal  $P_j \rho P_k$  may not vanish asymptotically.



### **Ensemble Evolution**

#### The trajectory averaged evolution is: $\frac{d}{dt}(P_j\rho P_k) = P_j\rho P_k g[w_j + w_k - 2\sum_i w_i Tr(P_i\rho)].$

Diagonal projections of  $\rho$  fully determine the evolution:  $\frac{2}{P_j\rho P_k}\frac{d}{dt}(P_j\rho P_k) = \frac{1}{P_j\rho P_j}\frac{d}{dt}(P_j\rho P_j) + \frac{1}{P_k\rho P_k}\frac{d}{dt}(P_k\rho P_k)$ 

For one-dimensional projections,  $P_j\rho(t)P_j = d_j(t)P_j$ ,

$$d_j \ge 0$$
,  $P_j \rho(t) P_k = P_j \rho(0) P_k \left[ \frac{d_j(t) d_k(t)}{d_j(0) d_k(0)} \right]^{1/2}$ 

Phases of the off-diagonal projections  $P_j \rho P_k$  do not change. Also, off-diagonal  $P_j \rho P_k$  may not vanish asymptotically.

The diagonal projections evolve according to:

$$\frac{d}{dt}d_j = 2g \ d_j(w_j - w_{\rm av}) \ , \ \ w_{\rm av} \equiv \sum_i w_i d_i \ .$$

Evolution is restricted to the subspace spanned by all the  $P_j\rho(t=0)P_j \neq 0$ . Diagonal elements with  $w_j > w_{\rm av}$  grow; those with  $w_j < w_{\rm av}$  decay. Every  $\rho = P_i$  is a fixed point.

Hardie Right Steam

All these features are stable under small perturbations of  $\rho$ .
### **Ensemble Evolution (contd.)**

Instantaneous Born rule:  $w_j = w_j^{IB} \equiv Tr(\rho(t)P_j)$ This is a local and appealing choice for the trajectory weights throughout the measurement process. Then  $\frac{d}{dt}(P_j\rho P_k) = P_j\rho P_k \ g[w_j^{IB} + w_k^{IB} - 2\sum_i (w_i^{IB})^2]$ .



### **Ensemble Evolution (contd.)**

Instantaneous Born rule:  $w_j = w_j^{IB} \equiv Tr(\rho(t)P_j)$ This is a local and appealing choice for the trajectory weights throughout the measurement process. Then  $\frac{d}{dt}(P_j\rho P_k) = P_j\rho P_k g[w_j^{IB} + w_k^{IB} - 2\sum_i (w_i^{IB})^2]$ .

The evolution converges towards the subspace specified by the dominant diagonal projections of  $\rho(t = 0)$ . This deterministic behaviour disagrees with observations, although the results are consistent under repetition.



### **Ensemble Evolution (contd.)**

Instantaneous Born rule:  $w_j = w_j^{IB} \equiv Tr(\rho(t)P_j)$ This is a local and appealing choice for the trajectory weights throughout the measurement process. Then  $\frac{d}{dt}(P_j\rho P_k) = P_j\rho P_k g[w_j^{IB} + w_k^{IB} - 2\sum_i (w_i^{IB})^2]$ .

The evolution converges towards the subspace specified by the dominant diagonal projections of  $\rho(t = 0)$ . This deterministic behaviour disagrees with observations, although the results are consistent under repetition.

Instead of heading towards the nearest fixed point, the trajectories can be made to wander around and explore other possibilities by adding noise to their dynamics.

Stochastic noise can be added to the quantum trajectory weights  $w_i$ , in a structure similar to the Langevin equation.

Size of noise has to be found, while retaining  $\sum_i w_i = 1$ .



## **Single Qubit Measurement**

The evolution equations simplify considerably for a qubit with  $|0\rangle$  and  $|1\rangle$  as the measurement eigenstates:

$$\begin{aligned} \frac{d}{dt}\rho_{00} &= 2g \ (w_0 - w_1)\rho_{00}\rho_{11} \ ,\\ \rho_{01}(t) &= \rho_{01}(0) \left[\frac{\rho_{00}(t)\rho_{11}(t)}{\rho_{00}(0)\rho_{11}(0)}\right]^{1/2} \ .\\ \end{aligned}$$
With  $\rho_{11}(t) &= 1 - \rho_{00}(t) \text{ and } w_1(t) = 1 - w_0(t), \text{ only one} \end{aligned}$ 

independent variable describes evolution of the system.



## **Single Qubit Measurement**

The evolution equations simplify considerably for a qubit with  $|0\rangle$  and  $|1\rangle$  as the measurement eigenstates:

$$\frac{d}{dt}\rho_{00} = 2g (w_0 - w_1)\rho_{00}\rho_{11} ,$$
  

$$\rho_{01}(t) = \rho_{01}(0) \left[\frac{\rho_{00}(t)\rho_{11}(t)}{\rho_{00}(0)\rho_{11}(0)}\right]^{1/2} .$$

With  $\rho_{11}(t) = 1 - \rho_{00}(t)$  and  $w_1(t) = 1 - w_0(t)$ , only one independent variable describes evolution of the system.

Adding unbiased white noise with spectral density  $S_{\xi}$  to the instantaneous Born rule, the trajectory weights become:

$$w_0 - w_1 = \rho_{00} - \rho_{11} + \sqrt{S_{\xi}} \xi$$
.  
 $\langle \xi(t) \rangle = 0$ ,  $\langle \xi(t)\xi(t') \rangle = \delta(t - t')$ 



## **Single Qubit Measurement**

The evolution equations simplify considerably for a qubit with  $|0\rangle$  and  $|1\rangle$  as the measurement eigenstates:

$$\frac{d}{dt}\rho_{00} = 2g \ (w_0 - w_1)\rho_{00}\rho_{11} \ ,$$

$$\rho_{01}(t) = \rho_{01}(0) \left[ \frac{\rho_{00}(t)\rho_{11}(t)}{\rho_{00}(0)\rho_{11}(0)} \right]^{1/2}$$

With  $\rho_{11}(t) = 1 - \rho_{00}(t)$  and  $w_1(t) = 1 - w_0(t)$ , only one independent variable describes evolution of the system.

Adding unbiased white noise with spectral density  $S_{\xi}$  to the instantaneous Born rule, the trajectory weights become:

$$w_0 - w_1 = \rho_{00} - \rho_{11} + \sqrt{S_{\xi}} \xi .$$
  
$$\langle \xi(t) \rangle = 0 , \quad \langle \xi(t)\xi(t') \rangle = \delta(t - t')$$

This is a stochastic differential process on [0, 1]. The fixed points at  $\rho_{00} = 0, 1$  are perfectly absorbing boundaries. A quantum trajectory would zig-zag through the interval before ending at one of the two boundary points.



Individual quantum evolution trajectories for the initial state  $\rho_{00} = 0.5$ , with measurement eigenstates  $\rho_{00} = 0, 1$ , and in presence of measurement noise satisfying  $gS_{\xi} = 1$ .



Let P(x) be the probability that the initial state with  $\rho_{00} = x$ evolves to the fixed point at  $\rho_{00} = 1$ . Then by symmetry,

$$P(0) = 0, P(0.5) = 0.5, P(1) = 1.$$

No noise :  $S_{\xi} = 0 \implies P(x) = \theta(x - 0.5)$ . Only noise :  $S_{\xi} \to \infty \implies P(x) = 0.5$ .



Let P(x) be the probability that the initial state with  $\rho_{00} = x$ evolves to the fixed point at  $\rho_{00} = 1$ . Then by symmetry,

$$P(0) = 0, P(0.5) = 0.5, P(1) = 1.$$

No noise :  $S_{\xi} = 0 \implies P(x) = \theta(x - 0.5)$ . Only noise :  $S_{\xi} \to \infty \implies P(x) = 0.5$ .

It is instructive to convert the stochastic evolution equations from the differential Stratonovich form to the Itô form that specifies forward evolutionary increments:

$$d\rho_{00} = 2g \ \rho_{00}\rho_{11}(\rho_{00} - \rho_{11})(1 - gS_{\xi})dt + 2g\sqrt{S_{\xi}} \ \rho_{00}\rho_{11} \ dW ,$$
  
$$\langle dW(t) \rangle = 0 , \ \langle (dW(t))^2 \rangle = dt .$$

The Wiener increment can be modeled as a random walk.



Let P(x) be the probability that the initial state with  $\rho_{00} = x$ evolves to the fixed point at  $\rho_{00} = 1$ . Then by symmetry,

$$P(0) = 0, P(0.5) = 0.5, P(1) = 1.$$

No noise :  $S_{\xi} = 0 \implies P(x) = \theta(x - 0.5)$ . Only noise :  $S_{\xi} \to \infty \implies P(x) = 0.5$ .

It is instructive to convert the stochastic evolution equations from the differential Stratonovich form to the Itô form that specifies forward evolutionary increments:

$$d\rho_{00} = 2g \ \rho_{00}\rho_{11}(\rho_{00} - \rho_{11})(1 - gS_{\xi})dt + 2g\sqrt{S_{\xi}} \ \rho_{00}\rho_{11} \ dW ,$$
  
$$\langle dW(t) \rangle = 0 , \ \langle (dW(t))^2 \rangle = dt .$$

The Wiener increment can be modeled as a random walk.

The first term produces drift in the evolution, while the second gives rise to diffusion. The evolution with no drift, i.e. the pure Wiener process with  $gS_{\xi} = 1$ , is rather special:  $\langle d\rho_{00} \rangle = 0 \Leftrightarrow$  Born rule is a constant of evolution.



Starting at x, one moves to  $x + \epsilon$  with some probability, moves to  $x - \epsilon$  with the same probability, and stays put otherwise. Balancing the probabilities,

 $P(x) = \alpha (P(x+\epsilon) + P(x-\epsilon)) + (1-2\alpha)P(x) .$ 



Starting at x, one moves to  $x + \epsilon$  with some probability, moves to  $x - \epsilon$  with the same probability, and stays put otherwise. Balancing the probabilities,

$$P(x) = \alpha (P(x + \epsilon) + P(x - \epsilon)) + (1 - 2\alpha)P(x)$$

The general solution, independent of the choice of  $\epsilon$ , is that P(x) is a linear function of x, which is the Born rule:

$$gS_{\xi} = 1, \ P(0) = 0, P(1) = 1 \implies P(x) = x$$

Specific choices of g,  $\alpha$ ,  $\epsilon$  only alter the rate of evolution, and not the asymptotic outcome.



Starting at x, one moves to  $x + \epsilon$  with some probability, moves to  $x - \epsilon$  with the same probability, and stays put otherwise. Balancing the probabilities,

$$P(x) = \alpha (P(x + \epsilon) + P(x - \epsilon)) + (1 - 2\alpha)P(x)$$

The general solution, independent of the choice of  $\epsilon$ , is that P(x) is a linear function of x, which is the Born rule:

$$gS_{\xi} = 1, \ P(0) = 0, P(1) = 1 \implies P(x) = x$$

Specific choices of g,  $\alpha$ ,  $\epsilon$  only alter the rate of evolution, and not the asymptotic outcome.

Numerical tests were performed for different values of  $gS_{\xi}$ .  $\frac{\rho_{00}(t+\tau)}{\rho_{11}(t+\tau)} = \frac{\rho_{00}(t)}{\rho_{11}(t)}e^{2g\tau\overline{w}}, \quad \overline{w} = \frac{1}{\tau}\int_{t}^{t+\tau}(w_0 - w_1)dt .$ With  $g\tau \ll 1$ ,  $\overline{w}$  was generated as a Gaussian random number with mean  $\rho_{00}(t) - \rho_{11}(t)$  and variance  $S_{\xi}/\tau$ . The data clearly show the special status of  $gS_{\xi} = 1$ .





Probability that the initial qubit state  $\rho_{00} = x$  evolves to the measurement eigenstate  $\rho_{00} = 1$ , for different values of the measurement noise. The  $gS_{\xi}$  values label the curves.



During measurement, the probability distribution  $p(\rho_{00}, t)$ of the quantum trajectories evolves according to the Fokker-Planck equation (with  $gS_{\xi} = 1$ ):

$$\frac{\partial p(\rho_{00},t)}{\partial t} = 2g \frac{\partial^2}{\partial^2 \rho_{00}} \left( \rho_{00}^2 (1-\rho_{00})^2 p(\rho_{00},t) \right) .$$



During measurement, the probability distribution  $p(\rho_{00}, t)$ of the quantum trajectories evolves according to the Fokker-Planck equation (with  $gS_{\xi} = 1$ ):

$$\frac{\partial p(\rho_{00},t)}{\partial t} = 2g \frac{\partial^2}{\partial^2 \rho_{00}} \left( \rho_{00}^2 (1-\rho_{00})^2 p(\rho_{00},t) \right) .$$

Its exact solution corresponding to  $p(\rho_{00}, 0) = \delta(x)$  has two non-interfering peaks with areas x and 1 - x, monotonically travelling to the boundaries  $\rho_{00} = 1$  and 0 respectively.



During measurement, the probability distribution  $p(\rho_{00}, t)$ of the quantum trajectories evolves according to the Fokker-Planck equation (with  $gS_{\xi} = 1$ ):

$$\frac{\partial p(\rho_{00},t)}{\partial t} = 2g \frac{\partial^2}{\partial^2 \rho_{00}} \left( \rho_{00}^2 (1-\rho_{00})^2 p(\rho_{00},t) \right) .$$

Its exact solution corresponding to  $p(\rho_{00}, 0) = \delta(x)$  has two non-interfering peaks with areas x and 1 - x, monotonically travelling to the boundaries  $\rho_{00} = 1$  and 0 respectively.

Let  $tanh(z) = 2\rho_{00} - 1 \text{ map } \rho_{00} \in [0, 1] \text{ to } z \in (-\infty, \infty).$ Then the two peaks are diffusing Gaussians, with their centres at  $tanh^{-1}(2x - 1) \pm gt$  and variance gt.

They reach the boundaries only asymptotically.



During measurement, the probability distribution  $p(\rho_{00}, t)$ of the quantum trajectories evolves according to the Fokker-Planck equation (with  $gS_{\xi} = 1$ ):

$$\frac{\partial p(\rho_{00},t)}{\partial t} = 2g \frac{\partial^2}{\partial^2 \rho_{00}} \left( \rho_{00}^2 (1-\rho_{00})^2 p(\rho_{00},t) \right) .$$

Its exact solution corresponding to  $p(\rho_{00}, 0) = \delta(x)$  has two non-interfering peaks with areas x and 1 - x, monotonically travelling to the boundaries  $\rho_{00} = 1$  and 0 respectively.

Let  $tanh(z) = 2\rho_{00} - 1 \text{ map } \rho_{00} \in [0, 1] \text{ to } z \in (-\infty, \infty).$ Then the two peaks are diffusing Gaussians, with their centres at  $tanh^{-1}(2x - 1) \pm gt$  and variance gt.

They reach the boundaries only asymptotically.

The formal "measurement time" can be made finite by a (non-unique) change of variables, e.g.  $s = \tanh(gt) \in [0, 1]$ .

$$1 - s^2)\frac{d}{ds}\rho_{00} = 2(\rho_{00} - \rho_{11} + \sqrt{1 - s^2\xi})\rho_{00}\rho_{11}$$

The time-dependent coupling  $g o 1/(1-s^2)$  gives the same equation. Weak Measurements and Born Rule – p. 20

Preceding results are valid for binary orthogonal measurements on any quantum system, with the replacement  $\rho_{ii} \rightarrow Tr(\rho P_i)$ .



Preceding results are valid for binary orthogonal measurements on any quantum system, with the replacement  $\rho_{ii} \rightarrow Tr(\rho P_i)$ .

Projection operators for nonbinary orthogonal measurements can be expressed as a product of mutually commuting binary projection operators. Then each binary projection would have its own stochastic noise.



Preceding results are valid for binary orthogonal measurements on any quantum system, with the replacement  $\rho_{ii} \rightarrow Tr(\rho P_i)$ .

Projection operators for nonbinary orthogonal measurements can be expressed as a product of mutually commuting binary projection operators. Then each binary projection would have its own stochastic noise.

Another option for *n*-dimensional quantum measurements is to use the orthonormal set of weights in the convention of SU(n) Cartan generators (k = 1, ..., n - 1):

 $\sum_{i=0}^{k-1} w_i - kw_k = \sum_{i=0}^{k-1} \rho_{ii} - k\rho_{kk} + \sqrt{\frac{k(k+1)S_{\xi}}{2}} \xi_k ,$ where  $\xi_k$  are independent white noise terms.



Preceding results are valid for binary orthogonal measurements on any quantum system, with the replacement  $\rho_{ii} \rightarrow Tr(\rho P_i)$ .

Projection operators for nonbinary orthogonal measurements can be expressed as a product of mutually commuting binary projection operators. Then each binary projection would have its own stochastic noise.

Another option for *n*-dimensional quantum measurements is to use the orthonormal set of weights in the convention of SU(n) Cartan generators (k = 1, ..., n - 1):

 $\sum_{i=0}^{k-1} w_i - kw_k = \sum_{i=0}^{k-1} \rho_{ii} - k\rho_{kk} + \sqrt{\frac{k(k+1)S_{\xi}}{2}} \xi_k ,$ 

where  $\xi_k$  are independent white noise terms.

The condition for the evolution to be a pure Wiener process, and hence satisfy the Born rule, remains  $gS_{\xi} = 1$ .



• Individual quantum trajectories evolve unitarily, even in presence of noise. Mixed states arise when multiple trajectories with different noise histories are combined.



• Individual quantum trajectories evolve unitarily, even in presence of noise. Mixed states arise when multiple trajectories with different noise histories are combined.

• The trajectory weights  $w_i$  are real, but are not restricted to [0, 1]. They cannot be considered probabilities.



• Individual quantum trajectories evolve unitarily, even in presence of noise. Mixed states arise when multiple trajectories with different noise histories are combined.

- The trajectory weights  $w_i$  are real, but are not restricted to [0, 1]. They cannot be considered probabilities.
- Each noise history  $w_i(t)$  can be associated with an individual experimental run, and can be also be viewed as one of the many worlds in the ensemble.



• Individual quantum trajectories evolve unitarily, even in presence of noise. Mixed states arise when multiple trajectories with different noise histories are combined.

- The trajectory weights  $w_i$  are real, but are not restricted to [0, 1]. They cannot be considered probabilities.
- Each noise history  $w_i(t)$  can be associated with an individual experimental run, and can be also be viewed as one of the many worlds in the ensemble.

• When the Born rule is satisfied, attraction to measurement eigenstates scales as g while the noise scales as  $\sqrt{g}$ . This relation is local between the system and the apparatus.



• Individual quantum trajectories evolve unitarily, even in presence of noise. Mixed states arise when multiple trajectories with different noise histories are combined.

• The trajectory weights  $w_i$  are real, but are not restricted to [0, 1]. They cannot be considered probabilities.

• Each noise history  $w_i(t)$  can be associated with an individual experimental run, and can be also be viewed as one of the many worlds in the ensemble.

• When the Born rule is satisfied, attraction to measurement eigenstates scales as g while the noise scales as  $\sqrt{g}$ . This relation is local between the system and the apparatus.

• Measurement outcomes are independent of  $\rho_{i\neq j}$ , and so are unaffected by decoherence. Noise can be added to the phases of  $\rho_{i\neq j}$  without spoiling the described evolution of  $\rho_{ii}$ . The Born rule imposes no constraint on that noise.

## **Summary**

The quadratically nonlinear quantum Langevin equation for state collapse supplements the Schrödinger evolution:

 $\frac{d}{dt}\rho = \sum_{i} w_i g[\rho P_i + P_i \rho - 2\rho Tr(\rho P_i)].$ 

The weights  $w_i$  contain attraction towards measurement eigenstates and stochastic white noise. Fixing their ratio, i.e.  $gS_{\xi} = 1$ , makes the Born rule a constant of evolution.



## **Summary**

The quadratically nonlinear quantum Langevin equation for state collapse supplements the Schrödinger evolution:

 $\frac{d}{dt}\rho = \sum_{i} w_i g[\rho P_i + P_i \rho - 2\rho Tr(\rho P_i)].$ 

The weights  $w_i$  contain attraction towards measurement eigenstates and stochastic white noise. Fixing their ratio, i.e.  $gS_{\xi} = 1$ , makes the Born rule a constant of evolution.

The precise relation between the magnitude of the noise and the system-apparatus coupling governing the collapse time scale, points to a common origin for the two. The dynamics is closed and local; different interacting system-apparatus pairs can have different couplings.

It is not a universal background dynamics.



## **Summary**

The quadratically nonlinear quantum Langevin equation for state collapse supplements the Schrödinger evolution:

 $\frac{d}{dt}\rho = \sum_{i} w_i g[\rho P_i + P_i \rho - 2\rho Tr(\rho P_i)].$ 

The weights  $w_i$  contain attraction towards measurement eigenstates and stochastic white noise. Fixing their ratio, i.e.  $gS_{\xi} = 1$ , makes the Born rule a constant of evolution.

The precise relation between the magnitude of the noise and the system-apparatus coupling governing the collapse time scale, points to a common origin for the two. The dynamics is closed and local; different interacting system-apparatus pairs can have different couplings.

It is not a universal background dynamics.

It is a challenge to unify the two dynamical contributions in a fundamental underlying theory of quantum measurements.



• What underlying dynamics can simultaneously produce attraction towards measurement eigenstates (geodesic evolution) and irreducible noise (stochastic fluctuations)?

These features appear in variational principles and path integral framework.

Non-abelian gauge theories and general relativity also have quadratic nonlinearities.



• What underlying dynamics can simultaneously produce attraction towards measurement eigenstates (geodesic evolution) and irreducible noise (stochastic fluctuations)?

These features appear in variational principles and path integral framework. Non-abelian gauge theories and general relativity also have quadratic nonlinearities.

• Can the measurement dynamics be converted/extended to the quantum field theory language, e.g. exchange of quanta between the system and the apparatus?



• What underlying dynamics can simultaneously produce attraction towards measurement eigenstates (geodesic evolution) and irreducible noise (stochastic fluctuations)?

These features appear in variational principles and path integral framework. Non-abelian gauge theories and general relativity also have quadratic nonlinearities.

- Can the measurement dynamics be converted/extended to the quantum field theory language, e.g. exchange of quanta between the system and the apparatus?
- Are there generalisations that would allow the noise to be bypassed or modified under some unusual conditions?



• What underlying dynamics can simultaneously produce attraction towards measurement eigenstates (geodesic evolution) and irreducible noise (stochastic fluctuations)?

These features appear in variational principles and path integral framework. Non-abelian gauge theories and general relativity also have quadratic nonlinearities.

- Can the measurement dynamics be converted/extended to the quantum field theory language, e.g. exchange of quanta between the system and the apparatus?
- Are there generalisations that would allow the noise to be bypassed or modified under some unusual conditions?

• Incomplete measurements can test the dynamics of quantum state collapse. Experiments would require determination of the density matrix evolution, using weak measurements and with highly suppressed decoherence.



Such tests are becoming technologically feasible! Superconducting qubit experiments need to be extended to larger quantum systems.

#### References

- 1. G. Lindblad, On the generators of quantum dynamical subgroups.
- Comm. Math. Phys. 48, 119-130 (1976).

2. V. Gorini, A. Kossakowski and E.C.G. Sudarshan, Completely positive semigroups of N-level systems. J. Math. Phys. **17**, 821-825 (1976).

- 3. D. Giulini, E. Joos, C. Kiefer, J. Kuptsch, I.-O. Stamatescu and H.D. Zeh, Decoherence and the Appearance of a Classical World in Quantum Theory (Springer, 1996).
- 4. H.M. Wiseman and G.J. Milburn, Quantum Measurement and Control (Cambridge University Press, 2010).
- 5. B.S. DeWitt and N. Graham (Eds.), The Many-Worlds Interpretation of Quantum Mechanics, (Princeton University Press, 1973).
- 6. Y. Aharonov, D.Z. Albert and L. Vaidman, How the result of a measurement of a component of the spin of a spin-1/2 particle can turn out to be 100.
- Phys. Rev. Lett. 60, 1351-1354 (1988).
- 7. N. Gisin, Quantum measurements and stochastic processes
- Phys. Rev. Lett. 52 1657-1660 (1984);
- Stochastic quantum dynamics and relativity, Helvetica Physica Acts 62 363-371 (1989).
- 8. G. Ghirardi, Collapse theories,
- The Stanford Encyclopedia of Philosophy, E.N. Zalta (ed.) (2011).

http://plato.stanford.edu/archives/win2011/entries/qm-collapse/



## **References (contd.)**

9. A.N. Korotkov, Continuous quantum measurement of a double dot. Phys. Rev. B 60, 5737-5742 (1999); Selective quantum evolution of a qubit state due to continuous measurement. Phys. Rev. B 63, 115403-1 to 15 (2001).
10. R. Vijay, C. Macklin, D.H. Slichter, S.J. Weber, K.W. Murch, R. Naik, A.N. Korotkov and I. Siddiqi, Stabilizing Rabi oscillations in a superconducting qubit using quantum feedback. Nature 490, 77-80 (2012).

11. K.W. Murch, S.J. Weber, C. Macklin and I. Siddiqi, Observing single quantum trajectories of a superconducting quantum bit. Nature **502**, 211-214 (2013).

