Does CGLMP generalise Bell-CHSH in higher dimensions?

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The short answer? No.

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The Question

- CGLMP inequality as measure of non-locality ¹
 - Dimension dependent inequality for arbitrary dimensional systems
 - Exceeds Tsirelson bound $2\sqrt{2}$ for Bell inequality
 - ▶ Works along Werner line: maximally entangled state + noise
 - Implicitly assumed by experimentalists in the field to be a generalization of the Bell inequality for higher level systems [eg. Lo (2016)]
- Question: are there states that are Bell-CHSH non-local but are CGLMP local?
- Specifically constructed pure and mixed states that are maximally Bell non-local to see how CGLMP fares
- Result: Contrary to expectations, CGLMP fails to correctly identify a large family of maximally non-local Bell states

¹Kaszlikowski et. al., Phys. Rev. Lett. 85, 4418 (2000), Collins et. al., Phys. Rev. Lett. 88 040404 (2002)

A quick recap: The Bell-CHSH Inequality

- Consider: M × N level system with two subsystems A(B) of M(N) levels
- The Bell-CHSH operator: $\mathcal{B} = A_1B_1 A_1B_2 + A_2B_1 + A_2B_2$
 - $A_{1,2}$ and $B_{1,2}$ are local observables for the two subsystems
 - Conditions $-1 \leq \langle A_i \rangle \leq 1$ and $-1 \leq \langle B_i \rangle \leq 1$.
- ► Local hidden variable models constrain the Bell-CHSH function as inequality: $|\langle \mathcal{B} \rangle| \leq 2$
 - A violation implies non-locality.
 - QM as a non-local theory yields the upper bound to a value $2\sqrt{2}$ [Tsirelson (1980)].

▶ (Bound is absolute and independent of *M* and *N*)

The CGLMP prescription

 Analog of the Bell-CHSH operator: function I_N, defined for N × N level system by

$$I_N = \sum_{k=0}^{\lfloor N/2 \rfloor - 1} \left(1 - \frac{2k}{N-1} \right) \{ [P(A_1 = B_1 + k) + P(B_1 = A_2 + k + 1) + P(A_2 = B_2 + k) + P(B_2 = A_1 + k)] \\ - [P(A_1 = B_1 - k - 1) + P(B_1 = A_2 - k) + P(A_2 = B_2 - k - 1) + P(B_2 = A_1 - k - 1)] \}$$

- ► P(A_i, B_i) joint measurement probabilities for local observables A_i, B_i
- Measurement prescription ² involves two local observers, Alice and Bob
 - ► The measurement bases for the observables A_i and B_i; i = 1, 2 are of the form

$$\begin{aligned} |K\rangle_{A,i} &= \frac{1}{\sqrt{N}} \sum_{j=0}^{N-1} \exp\left(i\frac{2\pi}{N}j(K+\alpha_i)\right) |j\rangle_A \\ |L\rangle_{B,i} &= \frac{1}{\sqrt{N}} \sum_{j=0}^{N-1} \exp\left(i\frac{2\pi}{N}j(-L+\beta_i)\right) |j\rangle_B. \end{aligned}$$

- ▶ All the observables have integer eigenvalues $0, 1, \dots, N-1$.
- Tune variable phases α_i, β_i of the states depending on the measurements they choose

The CGLMP prescription (cont'd)

- Rules of classical probability $\implies |I_N| \leq 2$.
 - Interpreted as a locality condition; arises in measurements involving joint probabilities.
- ▶ For maximally entangled state, $I_{N \ge 3}$ exceeds Tsirelson bound
 - $I_{4 \max} = 2.8962$
 - $I_{N \to \infty} = 2.9696$
- ▶ Interpretation: since $I_4 > 2\sqrt{2}$ for the Bell state, it follows that some noisy states will obey Bell-CHSH but violate CGLMP
 - Led those authors to claim that CGLMP prescription is more general and stronger than the Bell-CHSH prescription
 - True along Werner line
 - Note: experiments are also performed on maximally entangled states

Numerical Probe

 Known conditions on local observables to hit Tsirelson bound [Braunstein (1992), Popescu (1992)]:

$$\begin{array}{ll} \left\langle A_{1,2}^2 \right\rangle &=& \left\langle B_{1,2}^2 \right\rangle = 1 \\ \left\langle \left\{ A_1, A_2 \right\} \right\rangle & {\rm or} & \left\langle \left\{ B_1, B_2 \right\} \right\rangle = 0. \end{array}$$
 (1)

- Conditions jointly constitute the definition of Clifford Algebra; the representations are essentially given by the standard Pauli matrices or their direct sums for each pair of observables.
- maximally non-local Bell states are either coherent, or incoherent superpositions of Bell states in mutually orthogonal 2 × 2 sectors. (Explains why there are no fully entangled Bell states when N is odd.)
- Conveniently choose the observables [SU(4) Sbaih (2013)]:

$$A_{1} = \frac{2}{\sqrt{3}}\lambda_{8} + \frac{\sqrt{6}}{3}\lambda_{15}; \quad A_{2} = (\lambda_{4} + \lambda_{11})$$

$$B_{1} = \frac{1}{\sqrt{2}}(A_{1} + A_{2}); \quad B_{2} = \frac{1}{\sqrt{2}}(A_{2} - A_{1}) \qquad (2)$$

Numerical Probe (cont'd)

Bell operator eigen-resolution:

$$\mathcal{B} = 2\sqrt{2}(\Pi_{\mathcal{H}_+} - \Pi_{\mathcal{H}_-}) \tag{3}$$

where $dim(\mathcal{H}_{\pm}) = 4$. The bases for \mathcal{H}_{+} may be chosen to be

$$\begin{aligned} |\eta_1\rangle &= \frac{1}{\sqrt{2}}(|11\rangle + |33\rangle); \quad |\eta_2\rangle &= \frac{1}{\sqrt{2}}(|10\rangle + |32\rangle)\\ |\eta_3\rangle &= \frac{1}{\sqrt{2}}(|01\rangle + |23\rangle); \quad |\eta_4\rangle &= \frac{1}{\sqrt{2}}(|00\rangle + |22\rangle) \end{aligned} \tag{4}$$

- Note: within each sector, all states, both pure and mixed. violate the Bell-CHSH inequality maximally.
- The Nelder-Mead optimization technique [Nelder 1965] employed to search for max I_4 per state,
 - Search over 4-D parameter space spanned by phases $\{\alpha_{1,2},\beta_{1,2}\}$
 - Note: Same technique used in CGLMP papers; numerical results verified

Pure States

Pure Bell state can take form

$$|\Psi
angle_{\mathcal{H}_{+}} = \sum_{i} c_{i} |\eta_{i}
angle \; ; \; \sum_{i} |c_{i}|^{2} = 1$$
 (5)

- 1000 pure states were sampled randomly through uniform distributions
 - Only 8.9% violated CGLMP



Figure : I_4 values for 1000 randomly sampled pure states, with a bin-width of 0.1. Red: Polynomial fit showing population decay. Black: $I_4 = 2$, demarcation between local and non-local states.

Mixed States

Sample 100 random mixed states of the form:

$$\rho_{\mathcal{H}_{+}} = \sum_{i} p_{i} |\eta_{i}\rangle \langle \eta_{i}|.$$
(6)

 The CGLMP prescription fails to identify non-locality, this time more dramatically



Figure : I_4 values for 100 randomly sampled mixed states, with a bin width 0.002.

This isn't surprising. Let's see why.

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Significance of Bell Inequalities



- Consider complete space of *behaviours* system, i.e., all possible sets of joint probabilities p={p(ab|xy)}: a, b –outputs, x, y inputs of the two subsystems. (Essentially the correlation space.)
- Can be broken up into three non-mutually exclusive categories, depending on conditions that are imposed on the overall system: no-signalling, local, and quantum

- The locality condition constitutes a polytope in the behaviour space, of whose vertices are local deterministic behaviours
- Hyperplanes characterising this polytope constitute a set of inequalities: reveal the non-local nature of a system depending on violation or satisfaction
- In the literature, this set is casually termed "the Bell inequalities" though in actuality they are facet inequalities, combinations of which create a Bell inequality
- One is the Bell-CHSH form and another is the CGLMP form
- In this way it is unsurprising that CGLMP is not a generalization of Bell-CHSH, and works along the Werner line in ways the Bell-CHSH falls short. They address different directions in the behaviour space. [Froissard (1981), Garg and Mermin (1984), Pitowsky (1989), Peres (1999), Werner and Wolf (2001)]

Conclusion

- Contrary to expectations, the CGLMP prescription fails to correctly identify a large family of maximally non-local Bell states
- The CGLMP and Bell-CHSH inequalities are merely two different facets of the Local polytope in the correlation space
- The family of facet inequalities (dubbed 'Bell inequalities' in literature) to give complete distinction of non-locality is as yet to be explored

Thank You



 No-signalling- Natural limitation that essentially implies: any local marginal probability of one subsystem is not influenced by the measurement setting of the second. Mathematically: ∑ p(ab|xy) = ∑ p(ab|xy') ∀ outputs a, b and inputs x, y, y'.
 [Tsirelson (1980), Popescu and Rohrlich (1994)]



Quantum− Consists of behaviours governed by QM, i.e., either
 1) a tensor product structure can be constructed between the two systems' positive operator valued measurements i.e.
 p(ab|xy) = tr(ρ_{AB}M_{a|x} ⊗ M_{b|y}) or 2) that their local observables as orthogonal projectors commute
 [M_{a|x}, M_{b|y}] = 0. [Tsirelson (1993)]



Local- Locality implies existence of a set of past factors λ shared by the two subsystems that taken together jointly and causally influence the outcomes of measurements performed on each part of the system. Formally, a Local Hidden Variable Theorem: p(ab|xy) = ∫_Λ dλq(λ)p(a|x, λ)p(b|y, λ), p(*|*, λ) - the local marginal probabilities, q(λ) - probability density of hidden variables λ in space Λ