Nongaussianities and features in multiple-field inflation

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Primordial features and nongaussianities

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What is this all about?

- Different methods for generating nongaussianities in multiplefield inflation.
 In contrast to single-field models, this consists of nonlinear
 - reprocessing of existing perturbations.
- Some typical classes of behaviour in these models.
 These show the effects which it is possible to get at the present state of the art.

Statistics of density perturbations



Statistics of density perturbations





Statistics of density perturbations

 $\langle \delta \phi^{\alpha}(\boldsymbol{k}_1) \delta \phi^{\beta}(\boldsymbol{k}_2) \rangle$ two-point function



during inflation, the comoving Hubble length decreases





Statistics of density perturbations



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We end up with a bundle of different trajectories

In a continuum approximation, we can describe the bundle statistically by calculating its moments



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Double quadratic inflation

 χ

$$V(\phi, \chi) = \frac{1}{2}m_{\phi}^{2}\phi^{2} + \frac{1}{2}m_{\chi}^{2}\chi^{2}$$

Planck units

/

$$(m_{\phi}, m_{\chi}) = (8.2, 12.9)$$

Rigopoulos, Shellard & van Tent astro-ph/0506704, astro-ph/0511041

Roll down steepest direction first

Later, the trajectory changes direction and begins to roll down the shallower direction

 $m_{\phi}/m_{\chi} = 9 \phi$



 $m_{\phi}/m_{\chi} = 9 \phi$



 $m_{\phi}/m_{\chi} = 9 \phi$

Gordon, Wands, Bassett & Maartens (2000)

Adjacent trajectories traverse the corner differently

There is some shear between trajectories





the corner differently



centroid

excursion

Cautionary note: We're not measuring distance on the plane, so length of the trajectory is *not* the relevant thing to think about







the corner differently



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$$P(s) = \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{1}{2}\frac{s^2}{\sigma^2}\right) \left[1 + \frac{\alpha}{6\sigma^3}H_3(s/\sigma)\right]$$

Gauss-Hermite series ("Gram-Charlier", "Edgeworth")

Contaldi & Magueijo (2001); Matarrese, Verde & Jimenez (2000), LoVerde et al. (2007)

This is the basic mechanism by which you generate multifield nongaussianity. It is a reprocessing effect

$$\zeta(\boldsymbol{x}) = \zeta[\zeta_g(\boldsymbol{x})] \approx \zeta_g(\boldsymbol{x}) + \frac{1}{2}\zeta'\zeta_g(\boldsymbol{x})^2 + \cdots$$

Because the reprocessing is local, the shape is local

In practice, our job is to calculate these moments

One can think of at least two methods



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One finds

• •

$$\zeta(\boldsymbol{x}) = \delta N = \frac{\partial N}{\partial \phi_{i*}} \delta \phi_{i*}(\boldsymbol{x}) + \frac{1}{2} \frac{\partial^2 N}{\partial \phi_{i*} \partial \phi_{j*}} \delta \phi_{i*}(\boldsymbol{x}) \delta \phi_{j*}(\boldsymbol{x}) + \cdot$$

Fourier transformation

$$\zeta(\mathbf{k}) = \delta N = \frac{\partial N}{\partial \phi_{i*}} \delta \phi_{i*}(\mathbf{k}) + \frac{1}{2} \frac{\partial^2 N}{\partial \phi_{i*} \partial \phi_{j*}} [\delta \phi_{i*} * \delta \phi_{j*}]_{\mathbf{k}} + \cdots$$

This is the "δN" method. It's good both analytically and numerically.

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This is the "δN" method. It's good both analytically and numerically.

To make use of this, one forms correlation functions of ζ and uses Wick's theorem

$$\langle \zeta(\mathbf{k}_1)\zeta(\mathbf{k}_2)\cdots\zeta(\mathbf{k}_n)\rangle \supseteq (\delta N \text{ prefactors}) \times \langle \delta\phi_*(\mathbf{k}_1)(\delta\phi*\delta\phi)_*(\mathbf{k}_2)\cdots\delta\phi_*(\mathbf{k}_n)\rangle$$

$$\langle \delta \phi_* \delta \phi_* \rangle \qquad \langle \delta \phi_* \delta \phi_* \rangle$$

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 $\langle \delta \phi_* \delta \phi_* \delta \phi_* \rangle$

This makes ζ a sum of correlation functions of the initial conditions

In fact, δN does two jobs for us



surface on which we care about the answer. *Really*, last scattering (usually we stop somewhere before)

Correlation functions of **ζ here** expressed in terms of correlation functions of the initial conditions here

spatially flat hypersurface

surface on which we give initial conditions we usually calculate correlation functions here, perturbatively in H/M_P and slow-roll parameters

In fact, δN does two jobs for us

I'm going to briefly change subject on the next slide, but this will come back later

comoving hypersurface

surface on which we care about the answer. Really, last scattering (usually we stop somewhere before)

 $\langle \delta \phi(\boldsymbol{k}_1) \delta \phi(\boldsymbol{k}_2) \delta \phi(\boldsymbol{k}_3) \rangle_{\eta} \supseteq \xi \ln |k\eta_*|$

Zaldarriaga (2003); DS, Lyth & Malik (2008); Mahajan & Rangarajan (2010) + talk today!

> cf. Renaux-Petel talk

 $O(\epsilon^2)$

spatially flat hypersurface

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surface on which we care about the answer. Really, last scattering (usually we stop somewhere before)

then, a gauge transformation is required

complicated time-dependent logs summed up to here

surface on which we give initial conditions we usually calculate correlation functions here, perturbatively in H/M_P and slow-roll parameters Alternatively, the picture of shearing trajectories implies there must be a formulation similar to geometrical optics, or a laser in a box (eg. nongaussian beams at LIGO)



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Mulryne, DS, Wesley (2009, 2010)

Transport of the probability distribution $I = \frac{u}{flow field} \qquad The trajectories are the integral curves of a flow field u$ $P = \frac{1}{\sqrt{2\pi\sigma}} \exp\left(-\frac{1}{2}\frac{s^2}{\sigma^2}\right) \left[1 + \frac{\alpha}{6\sigma^3}H_3(s/\sigma)\right]$

To work out how the distribution evolves under the flow, it is sufficient to impose conservation of probability

$$\frac{\mathrm{d}\boldsymbol{P}}{\mathrm{d}t} + \frac{\partial}{\partial\phi}\left(u\boldsymbol{P}\right) = 0$$

This is the continuity equation for fluid flow

Dilatation and shear-vorticity decomposition



The trajectories are the integral curves of a flow field **u**

$$\partial_i u_j = \frac{1}{3} \theta \delta_{ij} + \sigma_{ij}$$

dilatation shear-vorticity

Also, decompose Σ_{ij} similarly

$$\Sigma_{ij} = \frac{1}{3} \Sigma \delta_{ij} + \Omega_{ij}$$

sum of variances "covariance"

Dilatation and shear-vorticity decomposition



Dilatation and shear-vorticity decomposition



For example, in a shear-free flow — just isotropic expansion

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \right] = 2 \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{ij}\Omega_{ij}$$
$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \right] = 2 \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{ij}\Omega_{ij}$$
$$\Sigma = \Sigma_0 \exp\left(\frac{2}{3}\Theta(t)\right)$$

In other words, Σ depends only on the local integrated expansion of the flow

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$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right)\Omega_{ij} \right] = \frac{2}{3} \exp\left(-\frac{2}{3}\Theta(t)\right)\Sigma\sigma_{(ij)} + \exp\left(-\frac{2}{3}\Theta(t)\right)\sigma_{am}\Omega_{mb} \left[\delta_{ia}\delta_{jb} + \delta_{ib}\delta_{ja} - \frac{2}{3}\delta_{ab}\delta_{ij}\right]$$

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In other words, $\boldsymbol{\Sigma}$ depends only on the local integrated expansion

of the flow

expansion damping

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Omega_{ij} \right] = \frac{2}{3} \exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \sigma_{(ij)}$$

$$+\exp\left(-\frac{2}{3}\Theta(t)\right)\sigma_{am}\Omega_{mb}\left[\delta_{ia}\delta_{jb}+\delta_{ib}\delta_{ja}-\frac{2}{3}\delta_{ab}\delta_{ij}\right]$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \right] = 2 \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{ij}\Omega_{ij}$$
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 "isotropic"
growth
$$+ \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{am} \Omega_{mb} \left[\delta_{ia} \delta_{jb} + \delta_{ib} \delta_{ja} - \frac{2}{3} \delta_{ab} \delta_{ij} \right]$$

$$\frac{\mathrm{d}}{\mathrm{d}t} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \right] = 2 \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{ij}\Omega_{ij}$$
$$\Sigma = \Sigma_0 \exp\left(\frac{2}{3}\Theta(t)\right)$$

In other words, $\boldsymbol{\Sigma}$ depends only on the local integrated expansion

of the flow

$$\begin{aligned} & \underset{\text{damping}}{\text{expansion}} \\ & \underset{\text{d}}{\frac{d}{dt}} \left[\exp\left(-\frac{2}{3}\Theta(t)\right) \Omega_{ij} \right] = \frac{2}{3} \exp\left(-\frac{2}{3}\Theta(t)\right) \Sigma \sigma_{(ij)} \quad \text{``isotropic''} \\ & + \exp\left(-\frac{2}{3}\Theta(t)\right) \sigma_{am} \Omega_{mb} \left[\delta_{ia} \delta_{jb} + \delta_{ib} \delta_{ja} - \frac{2}{3} \delta_{ab} \delta_{ij} \right] \\ & \quad \text{anisotropic} \\ & \text{growth} \end{aligned}$$

None of this is particularly new, although this way of expressing it is

Gordon et <i>al</i> . 2001	decomposition into trajectories
Groot Nibbelink & van Tent (2001)	curved field space metric, vielbein adapted to the trajectories
Rigopoulos, Shellard & van Tent (2004, 2005)	first application of this picture to nongaussianities (as far as I know)
Byrnes, Choi & Hall (2008, 2009)	reverse engineer interesting trajectories
Peterson & Tegmark (2010a,b)	similar to N&vT, RS&vT, BC&H specialized to two fields

I want to compute some exciting nongaussianities! What do I do?

conventional δN (default) Typically need initial surface at horizon crossing. Computation of ∂φ(late)/∂φ(early) is trouble

Vernizzi & Wands (2006); Battefeld & Easther (2006); Meyers & Sivanandam (2010) + talk today!

Suyama, Tanaka & Yokoyama

> Mulryne, DS & Wesley

Use transport to get ϕ (late) in terms of ϕ (early). Use δN for gauge transform Suyama, Tanaka & Yokoyama (2007a,b)

Either use transport to get ϕ (late) in terms of ϕ (early) and δN for gauge transform, or transform to ζ immediately and do the calculation there



 ϕ





All these plots were made by David Mulryne (Imperial/QMUL)



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Double quadratic inflation: gauge/evolution split 0.6 gauge transform Peak value about $f_{NL} = 0.5$ 0.4 fields 0.2 0 f_{NL} -0.2 The small nongaussianity arises due to a large -0.4Peak value just under $f_{NL} = 0.5$ cancellation between the fields and the nonlinear -0.6 part of the gauge transformation -0.8 5 10 15 20 25 30 35 40 ()N (efoldings of inflation)



A model due to Byrnes, Choi & Hall $V = V_0 \chi^2 \exp(-\lambda \phi)$



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Turn a corner in field space. There is some dispersion and shear as you turn, but then refocusing, which tends to decrease f_{NL}. **Prediction:** likely negligible f_{NL} unless interrupted. (For me, this is the moral of Vernizzi & Wands)



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Disperse in field space. To limit the growth of f_{NL} , you have to eventually refocus eg., to an attractor like local thermal equilibrium (cf. Weinberg/Meyers) **Prediction:** depends whether you refocus before inflation ends, eg., by a hybrid transition

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Live with the necessity of an attractor! Do your best to change the value that f_{NL} converges to.

Prediction: reasonably unambiguous, but you can't make f_{NL} unboundedly large

In saying this, we're not really discovering anything new. The necessity has been well-understood for a long time, almost since people began to think seriously about multiple field inflation.

As has long been known, there can indeed be a large variation of ζ ... which can continue until a thermalized radiation-dominated universe has been established. Indeed, in models where one of the fields survives to the present Universe ... variation in ζ can continue right to the present. This variation is due to the presence on large scales of classical perturbations in both fields ... generated during inflation, and the effect of these must always be considered in a multi-component inflation model

Liddle, Lyth, Malik & Wands (1999) hep-ph/9912473

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When the trajectories refocus, f_{NL} does not usually converge to zero



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 $\frac{H}{\dot{\phi}}$

*

One definition of refocusing might be that the derivative $\partial \phi_c / \partial \phi^* \rightarrow 0$

(This is not always right)



Then, only this term is left. Often, but **not always**, it is small



Begin with an axion potential $V = \Lambda^4 \left(1 - \cos \frac{2\pi\phi}{f} \right)$



Alabidi & Lyth (2006), Kim & Liddle (2006), Battefeld & Easther (2006), Battefeld & Battefeld (2007) Begin with an axion potential $V = \Lambda^4 \left(1 - \cos \frac{2\pi\phi}{f}\right)$







 $\frac{6}{5}f_{\rm NL} \rightarrow \frac{3}{2}\epsilon_* - \eta_* + \epsilon_* f(k_i)$

 $f(k_i)$ is a complicated function of the $k_{\rm i}$ with well-defined limits, near the hilltop finite everywhere (Maldacena 2002) $V \approx 2\Lambda^4 \left(1 + \frac{\eta \delta}{2M_{\rm P}^2} \right)$ It turns out that $\epsilon_* \approx 0$ $\eta * \approx -2\pi^2 \frac{M_{\rm P}^2}{f^2}$


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Summary

- Typically, multifield inflation does not generate features in the sense they've been used so far. It generates transient spikes, bumps and wiggles in f_{NL}.
- f_{NL} is sourced by geometrical properties of the flow on field space. In all known examples (I believe) there is strong dispersion of trajectories (eg., BC&H models; ekpyrosis; KL&S hilltop model)
- Whether these are relevant depends on a prescription for ending inflation and what happens later. For example, if the trajectories are continuously dispersing, you have to say what makes them refocus.
- In some models, any f_{NL} generated during evolution can disappear due to refocusing of the trajectories.
- Many fields typically make ζ more gaussian unless one dominates